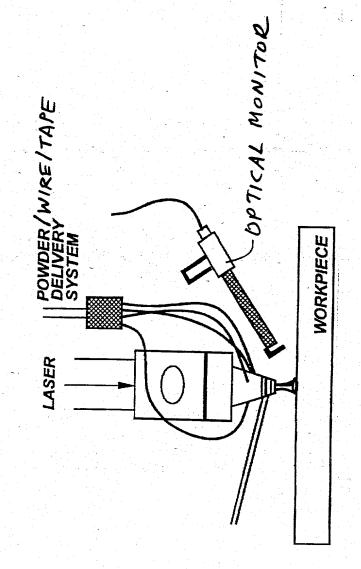




Figure - 2







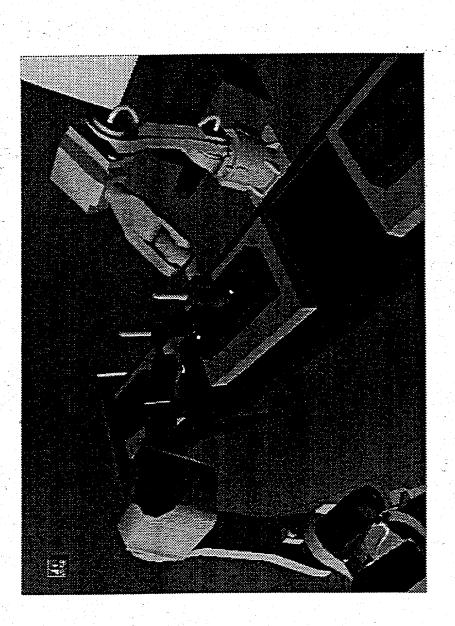


Figure 3. Robotic embodiment of DMD

FIGURE 4

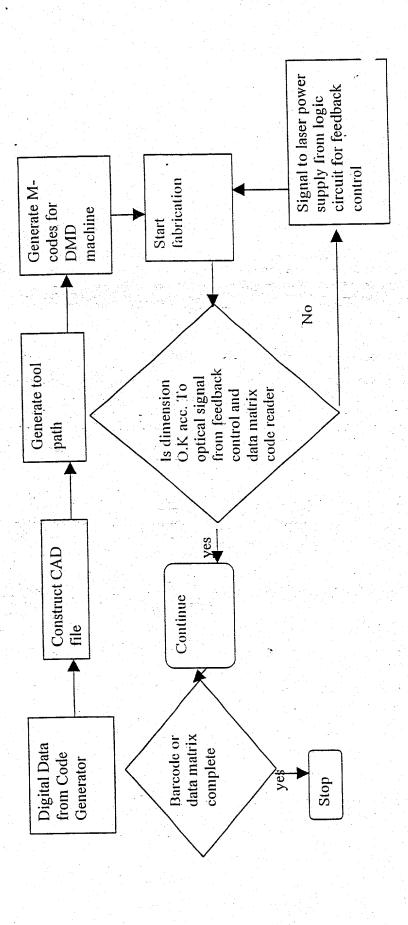


FIGURE 5



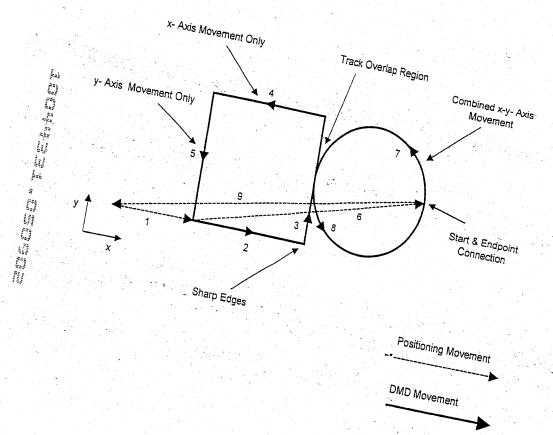
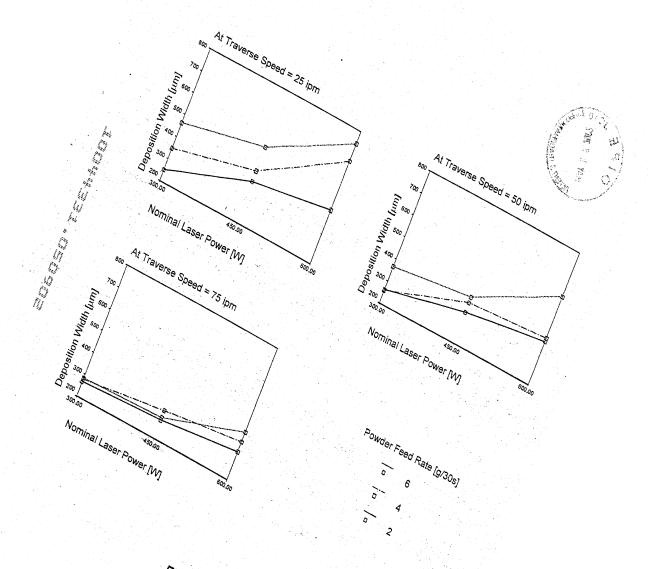
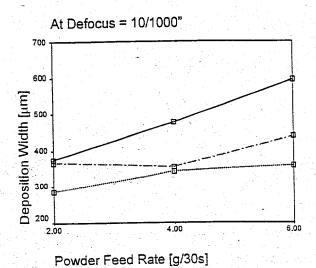


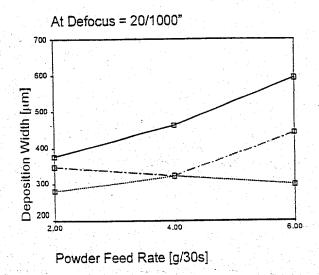
FIGURE 6

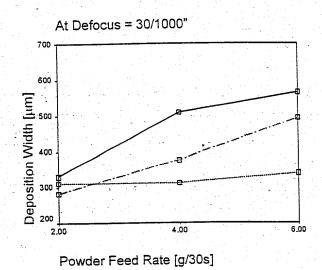


TIGURE >









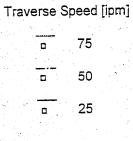
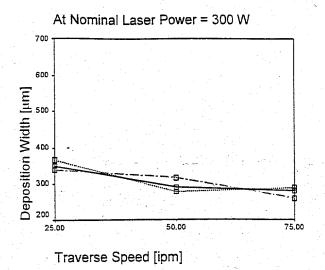
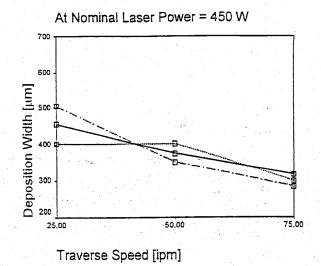
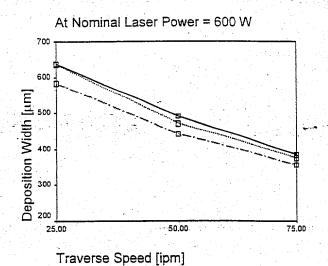


FIGURE 8









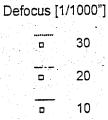
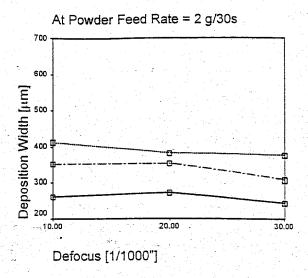
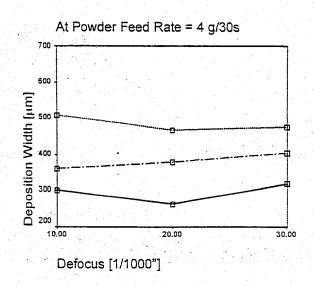
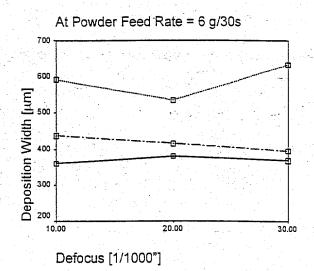


FIGURE 9









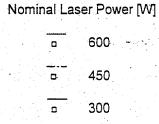
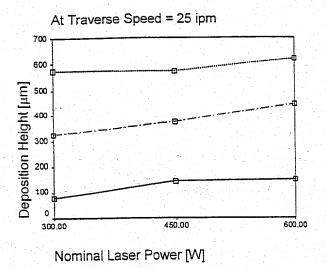
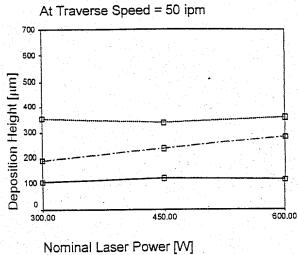
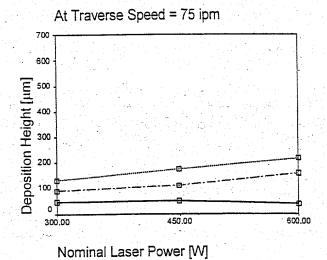


FIGURE 10









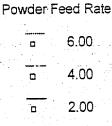
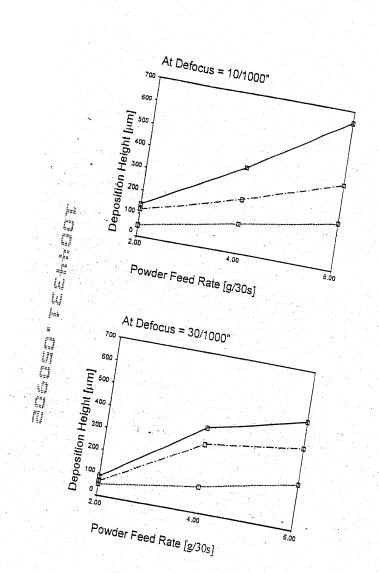
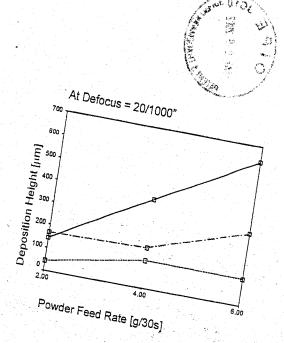
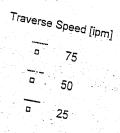


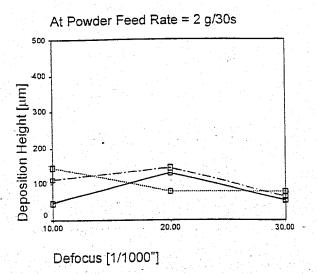
FIGURE 11

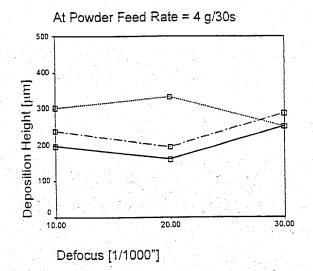


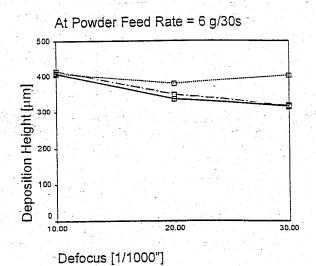












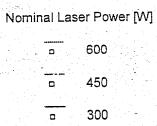
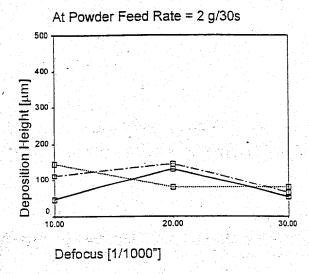
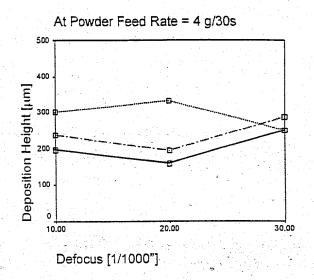
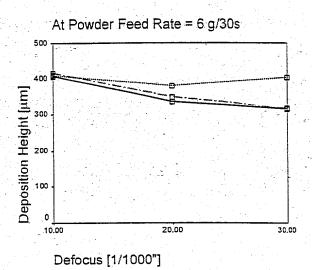


FIGURE 13







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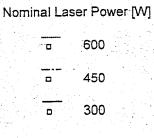


FIGURE 14